

Image credit: Hubble
telescope

Asymmetric Correlation Functions

Beyond LCDM

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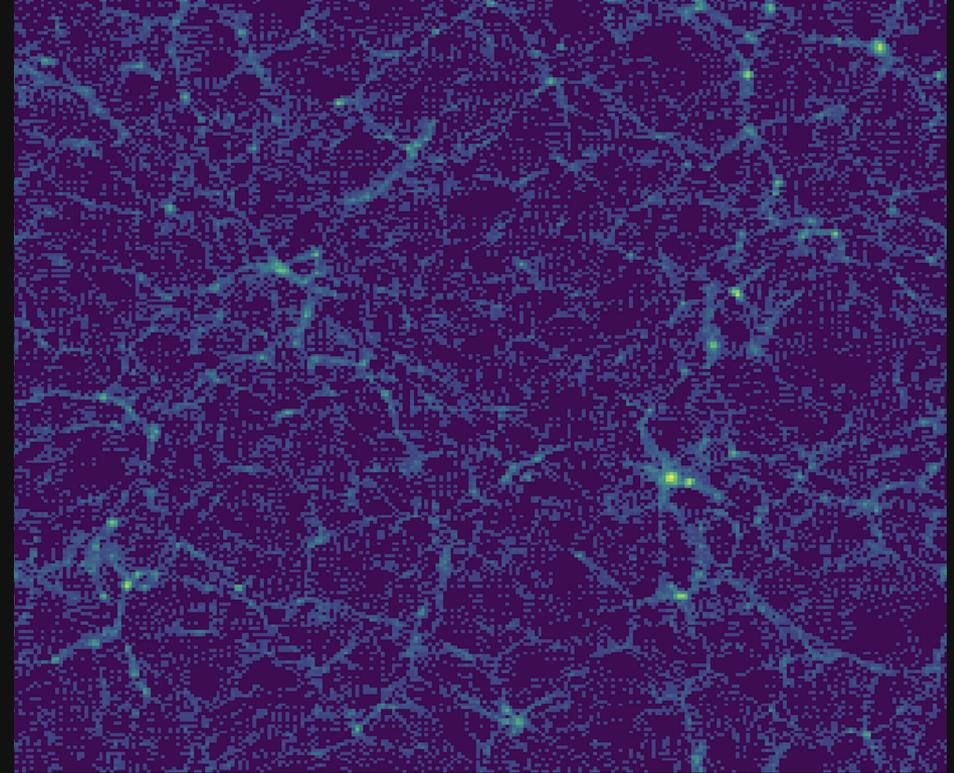
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Structure growth (LCDM)

- Inflation seeds a stochastic field

$$P_{\mathcal{R}}(\mathbf{k}) = \frac{2\pi^2}{k^3} \mathcal{A}_s(k\eta_0)^{n_s-1} \quad , \quad \left(\mathcal{R} = -\frac{aH}{\dot{\phi}} \delta\phi \right)$$

- The perturbations then evolve deterministically according to currently known physical laws.
- These two assumptions yield predictions for the properties of the observed density fields.



Correlation Functions

- A stochastic distribution can be inferred from a sample through its moments

$$\langle X^n \rangle = \int P(X) X^n dX$$

- A stochastic field is defined on a space of points, where each point has a degree of freedom that is sampled from the distribution. The points may be non-trivially related; Their relationship can be inferred using autocorrelation functions of the field

$$\langle X(\vec{x}) X(\vec{x} + \vec{d}) \rangle \equiv \xi(\vec{d}) = \int \frac{d^n x}{V^{(n)}} X(\vec{x}) X(\vec{x} + \vec{d})$$

- In our case, physics provides several tracers of the stochastic field, whose relations contain information about the physics that acts on on them. We can quantify their statistical relationship using cross-correlation functions

$$\langle Y(\vec{x}) Z(\vec{x} + \vec{d}) \rangle \equiv \xi(\vec{d}) = \int \frac{d^n x}{V^{(n)}} Y(\vec{x}) Z(\vec{x} + \vec{d})$$

Correlation Functions

- A Gaussian random field (GRF) has each point sampled from a Gaussian distribution. The points may be correlated. We can picture all the points as an infinite-dimensional vector

$$P(\vec{X}) = \frac{\exp\left(-\frac{1}{2}(\vec{X} - \vec{m})^T \mathbf{C}^{-1}(\vec{x} - \vec{m})\right)}{(2\pi)^{N/2}(\det \mathbf{C})^{1/2}}$$

- In the event of a GRF, we can uniquely determine it from its two first moments, or equivalently, from the mean vector and correlation matrix.
- Problem of tiny sample-size at each point is answered by cosmological principle and assumption of ergodicity.

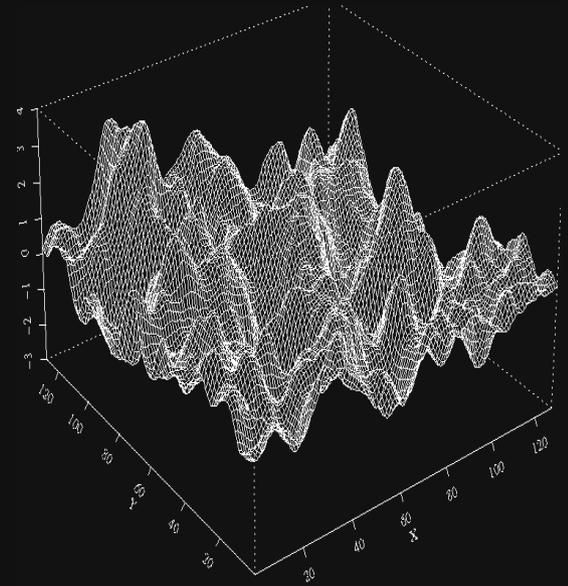


Image credit: Ben Kedem,
Maryland university

Survey Distortions

- In LCDM perturbation theory, we can relate the dark matter density field to the primordial curvature perturbations whose distribution we know from inflation. In Fourier space

$$D(k, \eta) = \mathcal{F}(\delta(x, \eta)) = -\frac{2}{3\Omega_m} \left(\frac{k}{\mathcal{H}_t}\right)^2 D(a) T(k) \sqrt{P_{\mathcal{R}}}$$

- Furthermore, using for example the Press-Schechter formalism, we can relate the number densities of non-linear structure, like halos or galaxies, to that of the dark matter density field. At first order $\delta_g = b\delta_{cdm}$
- Galaxy/halo counts can be done in satellite/telescope surveys. However there are complications in making the correct counts owing to survey volume distortions, due to among other propagation effects [Yoo et al. 2012, Bonvin and Durrer 2012].

Survey Distortions

- The Doppler effect changes the distance one would infer for the galaxy when one uses the redshift-distance relation.

Normally $r^{(c)} = \int \frac{cd a}{a^2 H}$ and $a = \frac{1}{1+z}$, and we measure z from spectrography.

Now, $a = \frac{\lambda_{emit}}{\lambda_{observ}} = \frac{\lambda_0(1 + \vec{v}_s \cdot \hat{n})}{\lambda_0(1+z)(1 + \vec{v}_O \cdot \hat{n})} \simeq \frac{1}{1+z} (1 + (\vec{v}_S - \vec{v}_O) \cdot \hat{n})$

- This translates to a distortion in the overdensity $\Delta^{std} = b\delta - \frac{1}{\mathcal{H}} \partial_r (\vec{v} \cdot \hat{n})$
- If we go to Fourier space, we recover the famous Kaiser formula [Kaiser 1987] (note angular dependency)

$$P_{XY}(k) = \langle \Delta_X \Delta_Y \rangle = P_{\delta\delta}(k) (b_X + f\mu^2) (b_Y + f\mu^2)$$

Survey Distortions

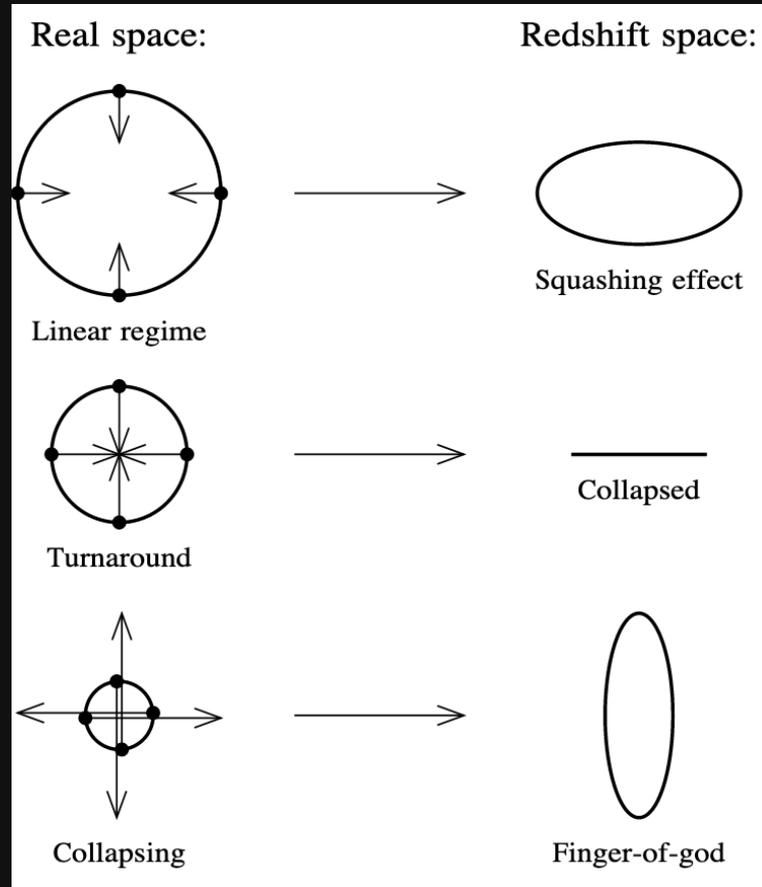
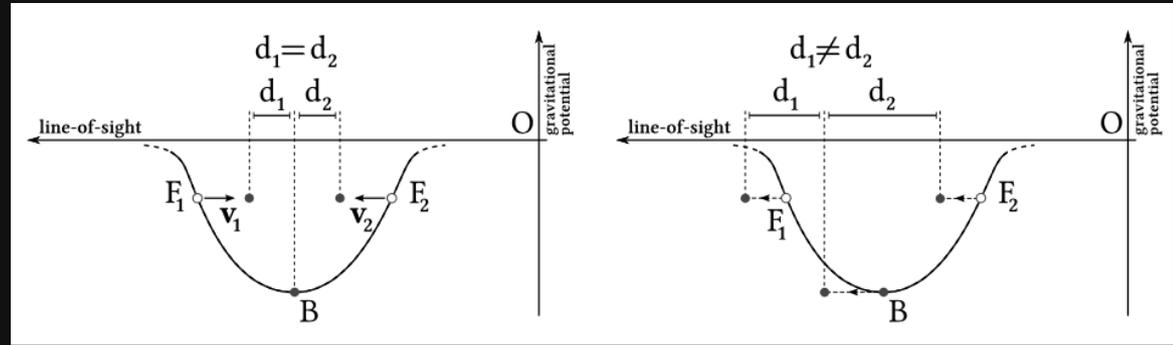


Image credit:
Hamilton
(1997)

$$\Delta^{(rel)} \supset \mathcal{H}^{-1} \partial_r \psi$$



$$\Delta^{(rel)} = \mathcal{H}^{-1} (\partial_r \psi + \dot{\mathbf{v}} \cdot \hat{\mathbf{n}}) - \left[\frac{\dot{\mathcal{H}}}{\mathcal{H}^2} + \frac{2}{r\mathcal{H}} - 1 + 5s \left(1 - \frac{1}{r\mathcal{H}} \right) \right] \mathbf{v} \cdot \hat{\mathbf{n}}$$

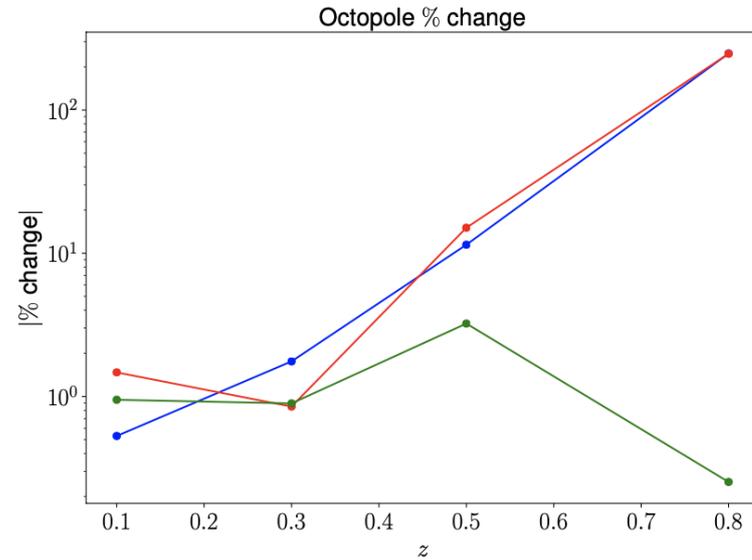
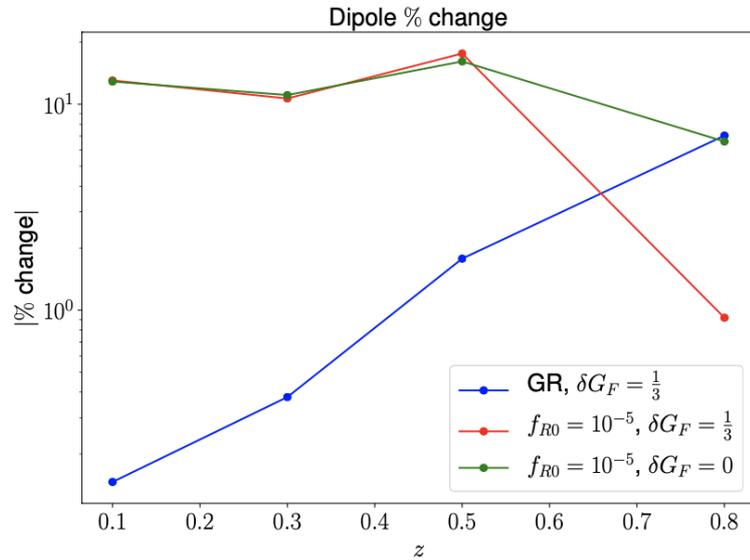
$$\Delta^{\text{lens}} = (5s - 2) \int_0^r dr' r' \left(\frac{r - r'}{2r} \right)$$

$$\Delta^{\text{AP}} = (\partial_r - \partial_\eta) \left[\sum_{i \neq \text{AP}} \Delta^{(i)} \right] \frac{dr}{d\vec{\Theta}} \delta \vec{\Theta}$$

$$\Delta = \sum \Delta^{(i)}$$

$$\partial_r \Psi \rightarrow (1 + \delta G) \partial_r \Psi,$$

$$\Delta^{\mathcal{F}}(z, \hat{\mathbf{n}}) = \zeta \left[\frac{\dot{\mathbf{v}} \cdot \hat{\mathbf{n}}}{\mathcal{H}} + \mathbf{v} \cdot \hat{\mathbf{n}} \right]$$



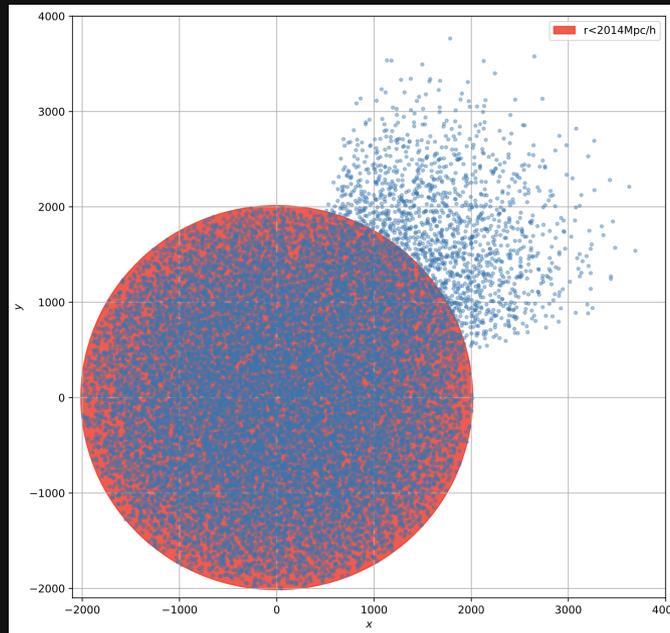
Kodwani & Desmond
(2019)

Effects of Beyond LCDM

- Since the odd multipoles seem sensitive to relativistic corrections, we might ask whether they would be to gravity modifications as well.
 - Equivalence principle violations/screening
[Bonvin and Fleury 2018, Kodwani and Desmond 2019]
 - Enhanced/suppressed clustering
 - Propagation effects
 - Other survey volume distortions
- Unique and clean signature? What are optimal tracers to cross-correlate?

Search for signatures in simulations

- Previous studies [Breton et al. 2019, Beutler and Dio 2020, Guandalin et al. 2021]
- Gevolution is a good choice for modelling of relativistic effects.
- Extracting observables on the lightcone is conceptually simplest as we are interested in distortions on the lightcone.
- We consider halos at first.

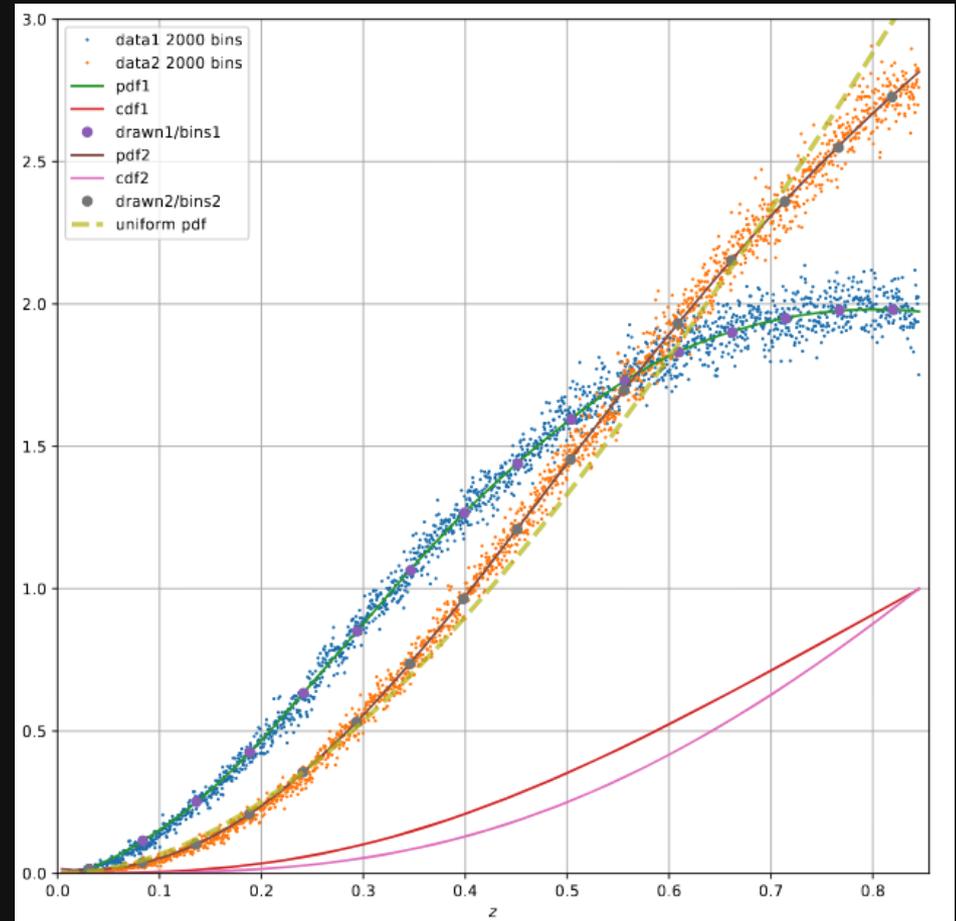


Constructing a random catalog

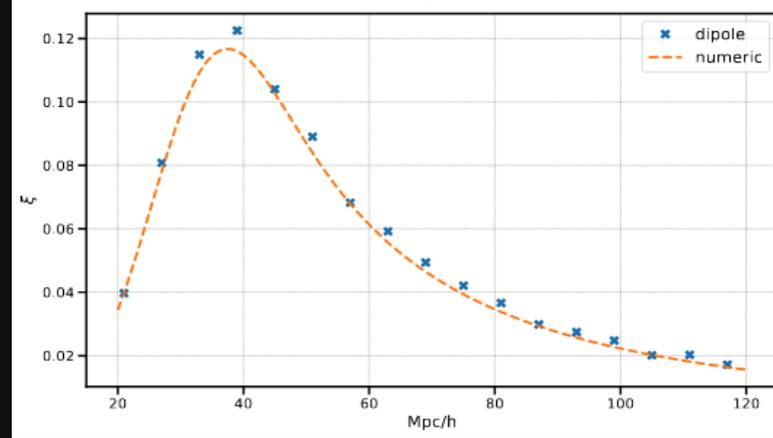
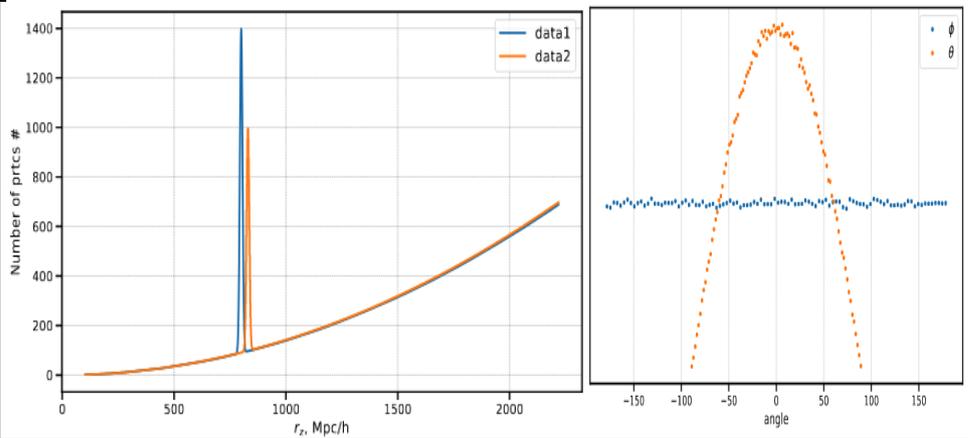
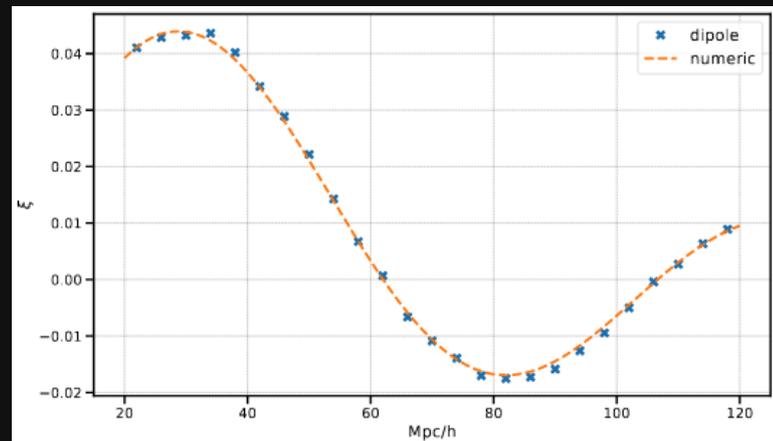
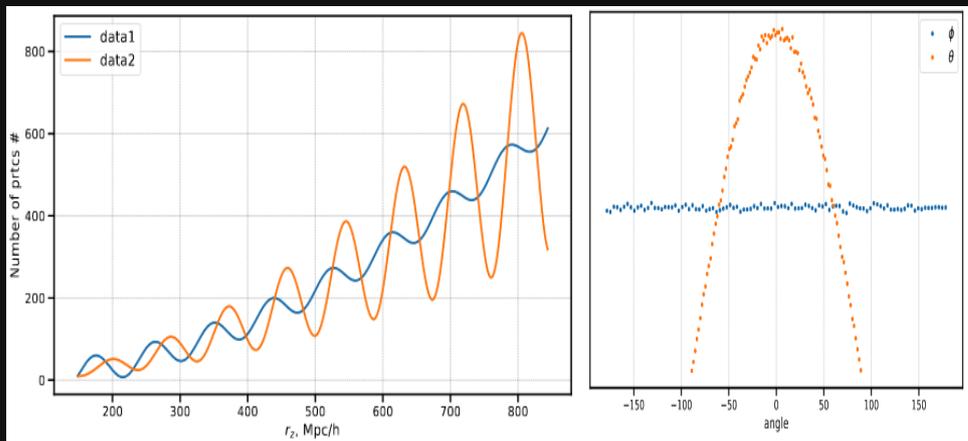
- Landay-Szalay estimator

$$\xi_{LS} = \frac{\langle (D_1 - R_1)(D_2 - R_2) \rangle}{\langle R_1 R_2 \rangle}$$

- Uniform distribution?
- Account for halo number evolution?



Artificial Datasets



Summary

- Inflation provides us with stochastic field.
- We can extract information through moments of tracers.
- Tracers are imprinted by physics.
- Estimators are distorted by physics.
 - Hopefully we can knead the data in a way to glean new physics and resolve all degeneracies.
- Towards this aim we may
 - Choose different cross-correlations
 - Project onto different functional bases
 - Consider different statistical moments
 - Subdivide and filter our data as we see fit
 - Vary how we model our random sets
 - Weighted estimators

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